

Improving Precision of Program Analysis in the 2LS Framework

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Motivation for This Work

2LS is a **verification framework** for analysing sequential C programs. Currenly, is usable for analysis of numerical and dynamic variables. Verification is based on computing invariants of source program by utilizing an SMT solver.

Due to **complexity** of computed invariants it is **hard** to identify parts of the original program that cause undecidability of verification.

We propose a solution, to **identify parts** of the original programs that cause problems to the verifier by analysing computed loop invariants.

Verification Example

Program written in C. Consists of two variables, one uinitialized and a simple loop.

Verification is inconclusive, user-specified assertion is *true* only if variable *y* is zero.

2LS Architecture

Parse

Tree:

id

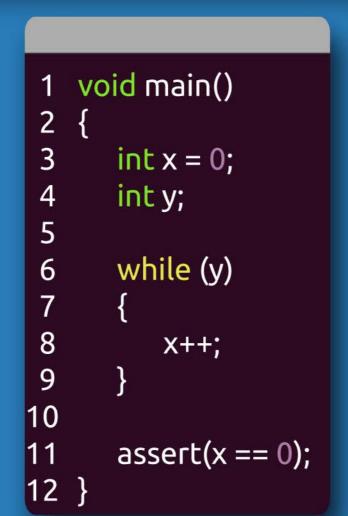
◆Position

Assignment

Expr

id

◆Initial



Expr

int

SSA Form

Expr

Imprecise Variable Identification

So-called *inductive invariants* are computed in various abstract domains using templates. Templates reduce the invariant inference problem so it can be iteratively solved using SMT solver.

We are looking for template variables that have values representing the *top* value in their abstract domains.

Numerical variables: finite max. values of their types Objects (static and dynamic): non-deterministic set of addresses

Invariant Generator

Interval domain

Analysis of numerical variables. Variable x and constant *d*:

$$(x \le d_1) \land (-x \le d_2)$$

Octagon domain

Heap domain

Analysis of objects on the heap, pointer *p*:

$$p \longrightarrow obj_1 obj_2$$

 $p = \&obj_1 \lor p = \&obj_2$

SMT Solver

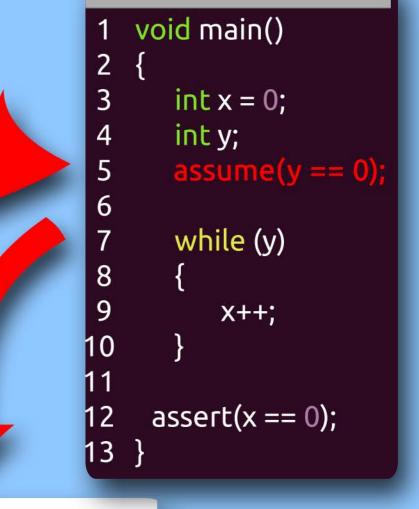
External solver, over CNF formula (translated SSA) using theory of bit-vectors.

Generated Invariant:

 $(x \le 2147483647) \land$ $(-x \le 2147483648)$

Variables: 1: x#lb5

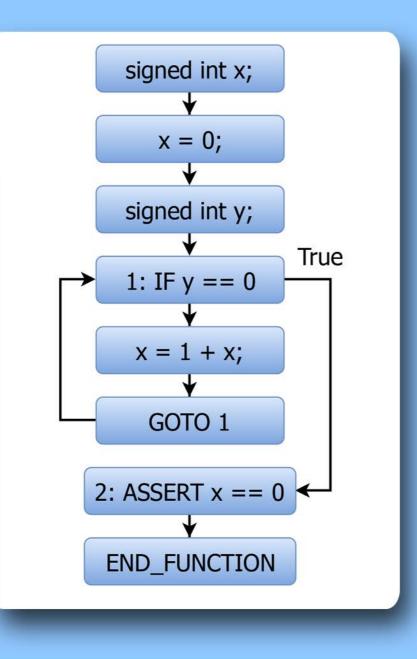
1: Imprecise value of variable "x" at the end of the loop, that starts at line 6



GOTO Conversion

C Parser

Intermediate program represenation using GOTO programs, which are control flow graphs. Various transformations, such as function inlining or light-weight static analysis to resolve function pointers, resulting in a static call graph.



loop head multiplexer $x_{phi3} = guard_{ls5} ? x_{lb5} : x_1$ loop body $x_4 = 1 + x_{phi3}$ end of the loop body Xlb5 after the loop

before the loop

 $x_1 = 0$

Acyclic *single static* assignment form. Satisfies the property that each variable is assigned to only once. Cuts the loops at the end of the loop body and introduces free variables.

Property Checker

Failed Unknown Success

[main.assertion.1] assertion x == 0: OK

- ** 0 of 1 unknown
- ** 0 of 1 failed
- **VERIFICATION SUCCESSFUL**